

ESOC's Multi-GNSS Processing

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Multi-GNSS Challenges

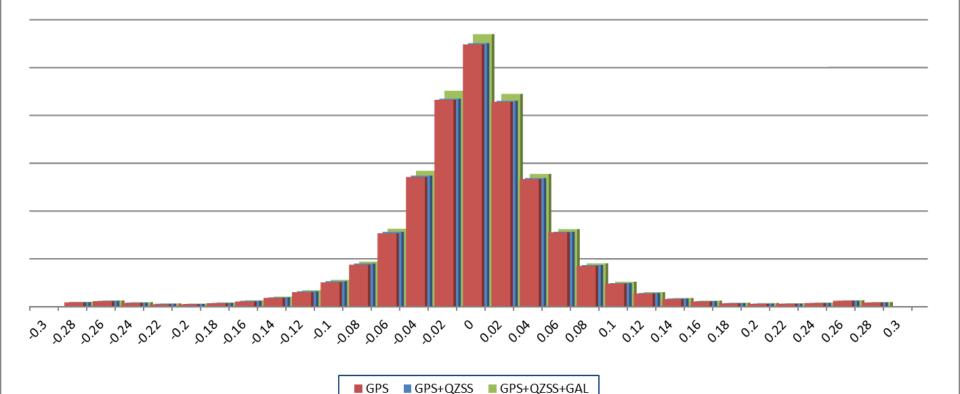


- 1. Lots of issues with new and additional frequencies and signals
 - a. Will be ignored in this presentation. IGS not ready !?
- 2. Integer Ambiguity Resolution
 - a. GPS L1-L2 P/C understood but how are the other signals
 - b. How about the other systems Galileo, GLONASS, BeiDou, QZSS
- 3. Satellite Attitude
 - a. Eclipse phases
 - b. Orbit normal mode for BeiDou and QZSS
 - Transition point/epoch from one mode to the other
- 4. Satellite Radiation Modelling (mainly Solar Radiation)
 - a. Simple box-wing
 - b. Elaborate satellite models
- 5. Satellite Transmitter Phase Centre
 - a. Location (PCO)
 - b. Variation as function of elevation and azimuth (PCV)

ESOC is systematically working to address all these issues

Integer Ambiguity Resolution Histogram of narrow lane fractionals





Integer Ambiguity Resolution



- 1. GPS L1 C/P L2 C/P understood
 - a. But how about L5C
 - There are issues with compatibility of the L1, L2, and L5 signals
- 2. How about the other systems
 - a. GLONASS
 - Only CODE does ambiguity resolution?
 - b. Galileo
 - Looks quite promising
 - c. BeiDou
 - Not working for us as MelWub fractionals not very good
 - Elevation dependent code biases part of the reason
 - d. QZSS
 - May be treated as a "normal" GPS satellite

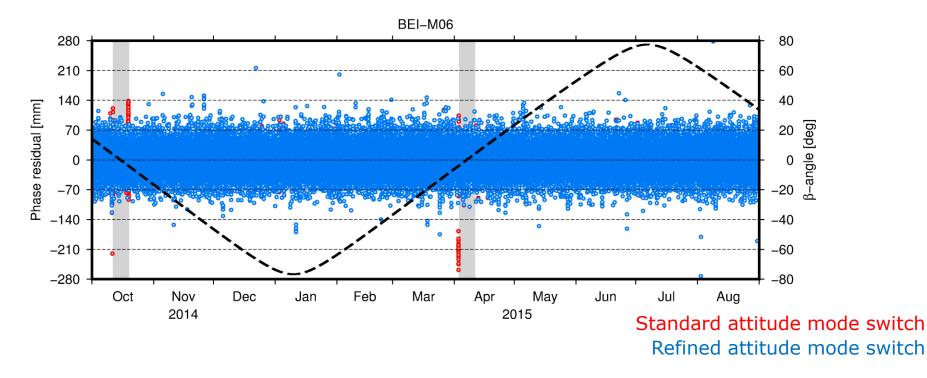
BeiDou attitude model



Potential attitude model improvement

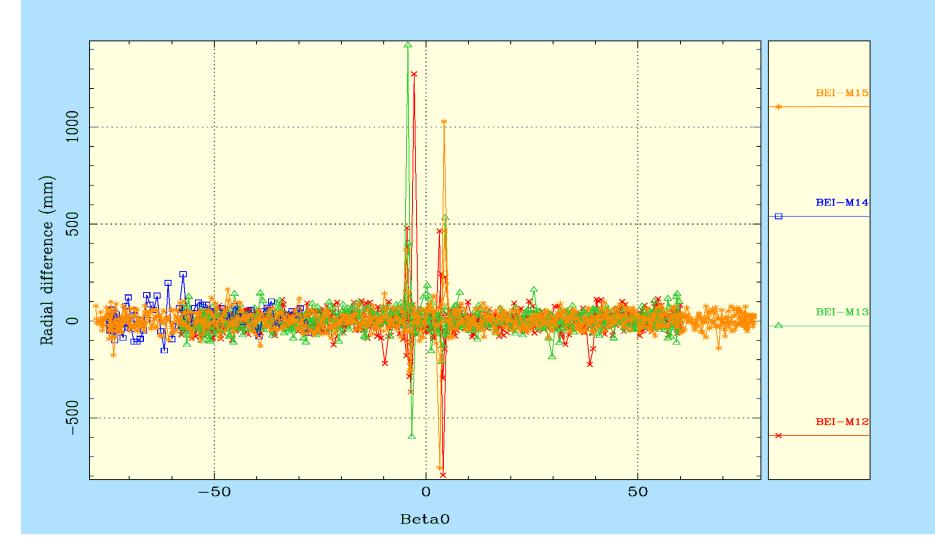
 \rightarrow Attitude transition from yaw steering to orbit normal mode

- Phase residuals show improvement
- Dedicated SLR tracking for transition periods could help to validate the attitude model



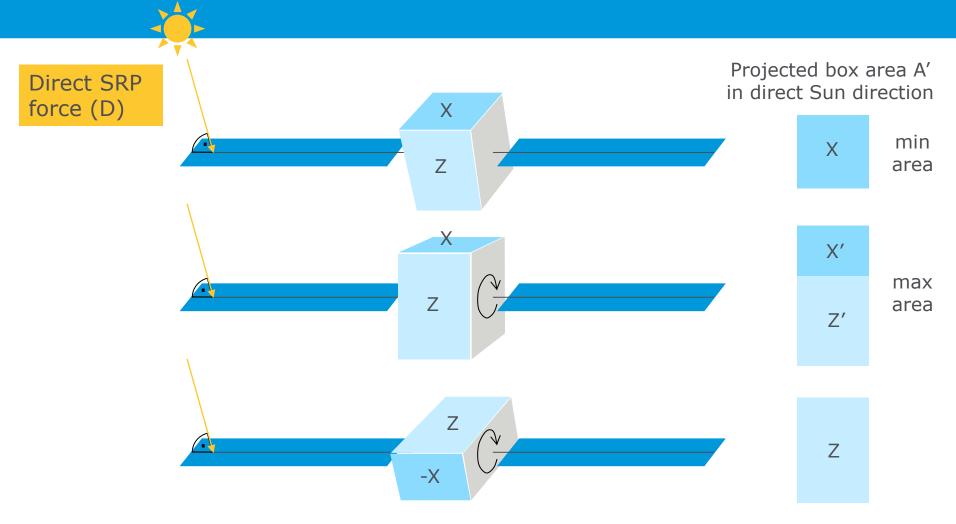
BeiDou attitude model Transition Issues





Solar radiation pressure





Acceleration due to direct SRP is assumed to be:

- constant for the wings $(A'_W = const)$
- but varying for the box $(A'_B = f(t))$

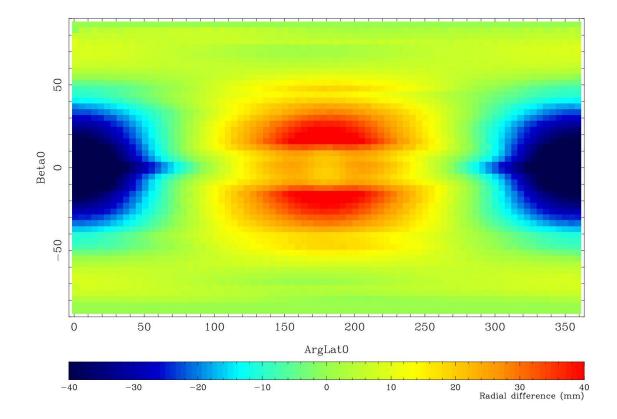
Approx. surface area changes Not absorbed by ECOM parameters



	max-min [m ²]			Mass [kg]	Impact	Sensit	
GPS-IIA	1.3				975	1.0	6
GPS-IIR/RM	1.8				1100	1.3	4
GPS-IIF	2.3				1450	1.2	5
GLONASS-M	2.8				1400	1.6	3
Galileo-1 (IOV)	2.0				695	2.2	2
BeiDou-M	1.5				2000	0.7	7
QZSS	12.2				2000	4.7	1

Radial orbit difference – GLONASS-M "with box-wing" minus "without box-wing"



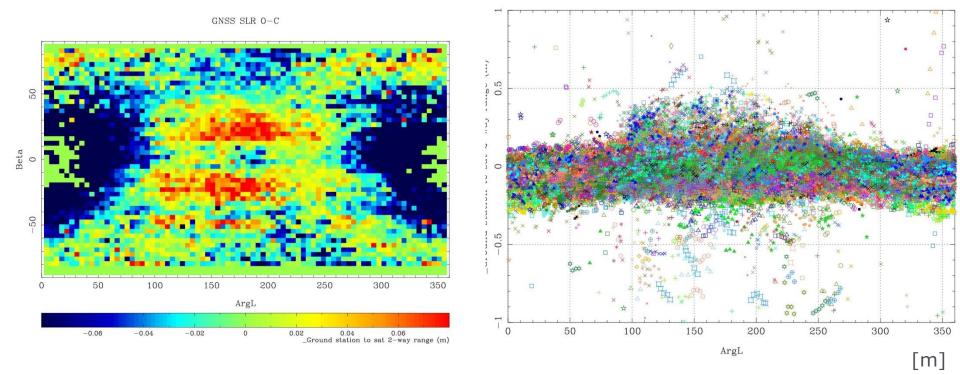


[mm]

SLR residuals (2-way) – GLONASS-M



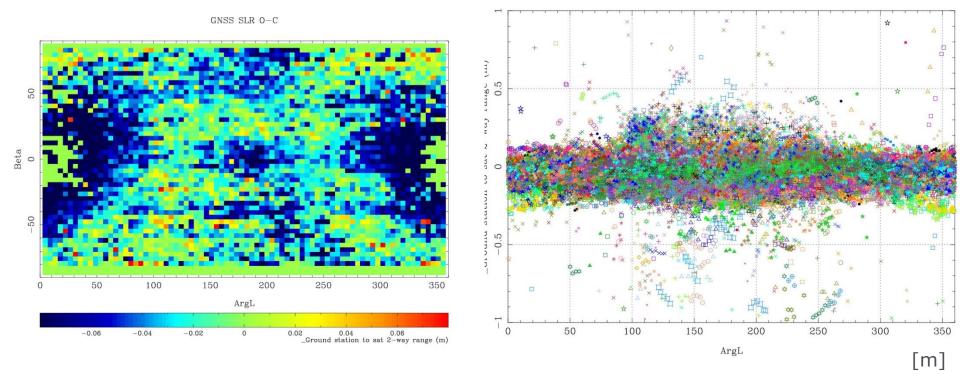
without box-wing



SLR residuals (2-way) – GLONASS-M

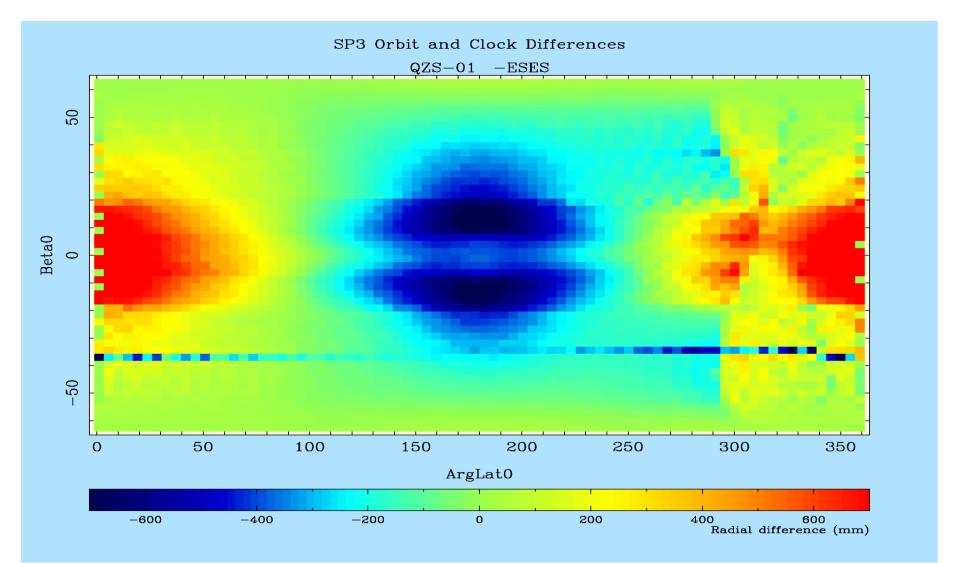


with box-wing

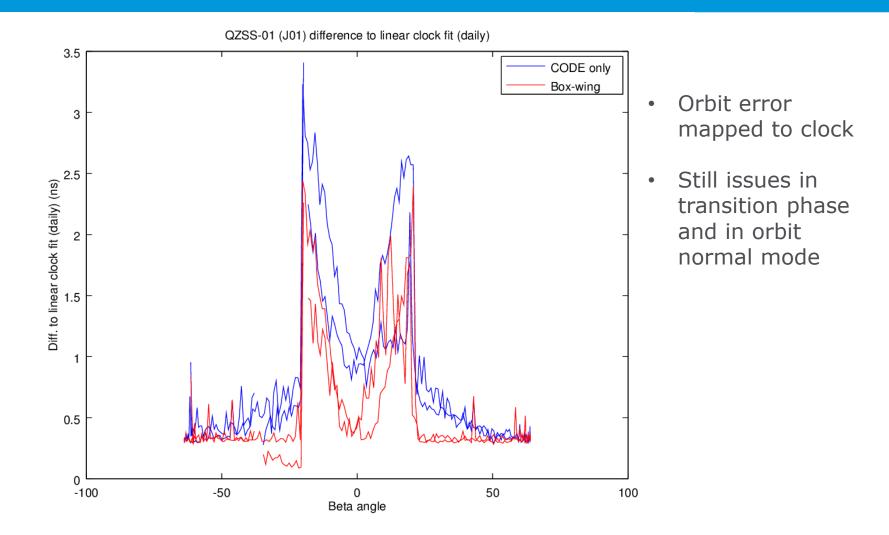


QZSS Radial Orbit Differences No Box-Wing versus Box-Wing





Impact of analytical SRP models (box-wing) CSS-01 difference of est. clock to linear fit (daily)



Satellite Attitude and Radiation Model

- 1. Orbit normal mode for BeiDou and QZSS:
 - a. BeiDou MEO and IGSO when |beta| < 4 degrees
 - b. QZSS when |beta| < 20 degrees
 - c. BeiDou GEO always
 - 1. Transition point/epoch from one mode to the other needed to be understood and modelled properly
 - 2. Good radiation pressure models for these satellites are needed
- 2. Every satellite type handles the eclipse phase differently:
 - a. Block II/IIA/IIR
 - b. Block IIF (which have also unexpected behaviour even outside eclipse)
 - c. GLONASS and Galileo rather similar
 - Some older GLONASS satellites have issues



Neither ECOM nor

ECOM2 model works

very well for this mode

Multi-GNSS Conclusions



Significant Efforts Needed for:

- 1. Integer Ambiguity Resolution Concepts
 - a. BeiDou and GLONASS
 - b. How about inter-system ambiguity resolution?
- 2. Satellite Attitude
 - a. GPS IIF issues
 - b. BeiDou and QZSS attitude transition
- 3. Satellite Radiation Modelling
 - a. Very important for QZSS and Galileo
 - b. Crucial for BeiDou and QZSS when in orbit normal mode
- 4. Transmit Antenna PCO/PCV
 - a. Estimates needed from different ACs
 - b. Also need to start worrying because of more than 2 freq's



THANK YOU

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